## Chains of theories

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This is work with Özcan Kasal. There is some parallel work by Alice Medvedev (presented in Oléron, June, 2011) concerning ACFA.

Suppose

$$
T_0 \subseteq T_1 \subseteq T_2 \subseteq \cdots,
$$

all theories, closed under entailment, so their signatures also form a chain:

 $\mathscr{S}_0 \subset \mathscr{S}_1 \subset \mathscr{S}_2 \subset \cdots$ 

In one example of interest,  $T_m$  is m-DF, the theory of fields with m commuting derivations  $\partial_0, \ldots, \partial_{m-1}$ ; their union is  $\omega$ -DF.

In general, what properties are preserved in  $\bigcup_{k\in\omega}T_k$ ? Compare:

**Theorem** (Chang, Łoś–Suszko). For a fixed theory  $T$ , the following are equivalent:

- 1. T is  $\forall \exists$ -axiomatizable.
- 2.  $Mod(T)$  is closed under taking unions of chains

$$
\mathfrak{A}_0\subseteq \mathfrak{A}_1\subseteq \mathfrak{A}_2\subseteq \cdots.
$$

Again, if  $T_0 \subseteq T_1 \subseteq T_2 \subseteq \cdots$ , then among possible properties of the theories  $T_k$ ,

- 1) Preserved by  $\bigcup_{k\in\omega}T_k$  are: (a) consistency, (b) completeness, (c) quantifier elimination, (d) model-completeness, (e) stability,  $(f)$  ...;
- ) not preserved (but this is not obvious) are: companionability,  $\omega$ -stability, superstability, ...
- (a) Consistency is preserved, by compactness.

(b) Completeness is preserved, because every sentence of the union  $\bigcup_{k\in\omega}\mathscr{S}_k$  is a sentence of some  $\mathscr{S}_k$ .

(c) Likewise for quantifier-elimination.

(d) **Model-completeness** of a theory T may be usually remembered as

 $A \subseteq \mathfrak{B} \implies A \preccurlyeq \mathfrak{B}$ 

within  $Mod(T)$ . Equivalently (the theory axiomatized by)

T ∪ diag(A)

is always complete when  $\mathfrak{A} \models T$ , where

diag( $\mathfrak{A}$ ) = { $\sigma \in \text{Th}(\mathfrak{A}_A)$ :  $\sigma$  is quanfifier-free}

the theory of the structures in which A embeds. A sufficient (and obviously necessary) condition is (Abraham) Robinson's Condition,

 $\mathfrak{A} \subseteq \mathfrak{B} \implies \mathfrak{A} \preccurlyeq_1 \mathfrak{B}$ 

where the conclusion means every quantifier-free formula over  $\mathfrak A$  soluble in  $\mathfrak{B}$  is soluble in  $\mathfrak{A}$ . Robinson's Condition is, equivalently,

$$
\mathfrak{A} \models_{\mathrm{ec}} T
$$

—every model of  $T$  is an existentially closed model. For this it is sufficient (and in fact necessary) that  $T$  admit quantifier-elimination down to ∃ formulas. Therefore model-completeness is preserved in unions of chains.

- (e) A *complete* theory  $T$  is
	- $\kappa$ -stable, if  $\kappa \geq |T|$  and

$$
|A| \leq \kappa \implies |\mathcal{S}(A)| \leq \kappa
$$

for all parameter-sets A of models of T;

- superstable, if  $\kappa$ -stable for  $\kappa$  large enough:
- stable, if  $\kappa$ -stable for some  $\kappa$ .

When  $|T| = \omega$ , then

- superstability implies  $\kappa$ -stability when  $\kappa \geq 2^{\omega}$ ;
- stability implies  $\kappa$ -stability when  $\kappa = \kappa^{\omega}$ .

(Note that if  $\text{cof}(\kappa) = \omega$ , as when  $\kappa = \aleph_{\omega}$ , then  $\kappa < \kappa^{\omega}$ .)

In fact *instability* of  $T$  is equivalent to the presence of a formula  $\varphi(\vec{x}, \vec{y})$  defining an infinite linear order in some model of T, so that, for all  $n$  in  $\omega$ ,

$$
T \vdash \exists (\vec{x}_0,\ldots,\vec{x}_n) \left( \bigwedge_{0 \leq i \leq j \leq n} \varphi(\vec{x}_i,\vec{x}_j) \land \bigwedge_{0 \leq j < i \leq n} \neg \varphi(\vec{x}_i,\vec{x}_j) \right).
$$

If  $T = \bigcup_{k \in \omega} T_k$ , then these sentences are all in some  $\mathscr{S}_k$ , and then (assuming  $T_k$  is complete)  $T_k$  will be instable.

An arbitrary theory  $T$  is **companionable** if, for some theory  $T^*$  of its signature,

- $T_{\forall} = T^*_{\forall}$
- $T$  is model-complete.

In this case,  $T^*$  is the **model-companion** of  $T$ . If

$$
T_0 \subseteq T_1 \subseteq T_2 \subseteq \cdots,
$$

and each  $T_k$  has the model-companion  $T_k^*$ , and

$$
T_0^* \subseteq T_1^* \subseteq T_2^* \subseteq \cdots,
$$
\n<sup>(\*)</sup>

then  $\bigcup_{k\in\omega}T_k^*$  is the model-companion of  $\bigcup_{k\in\omega}T_k$ . However  $(*)$ may fail.

**Theorem** (McGrail).  $m$ -DF<sub>0</sub> (in characteristic 0) has a modelcompanion, m- $DCF_0$ , which admits quantifier-elimination and is  $\omega$ stable.

Theorem (P.). m-DF has a model-companion, m-DCF. Nevertheless,  $\bigcup_{m\in\omega}$  m-DF is not companionable.

For the last part (non-companionability), if  $j \in \omega$ , let  $K_j$  be an e.c. (*existentially closed*) model of  $\omega$ -DF (that is,  $\bigcup_{m\in\omega} m$ -DF), with

$$
\mathbb{F}_p(\alpha) \subseteq K_j, \qquad \alpha \notin \mathbb{F}_p^{\text{alg}}, \qquad \partial_i \alpha = \delta_{ij} = \begin{cases} 1, & \text{if } i = j, \\ 0, & \text{if } i \neq j. \end{cases}
$$

Then  $\alpha$  has no p-th root in  $K_i$ , since

$$
\partial_j \alpha = 1, \qquad \qquad \partial_j (x^p) = p \cdot x^{p-1} \cdot \partial_j x = 0.
$$

Therefore  $\alpha$  has no p-th root in a nonprincipal ultraproduct

$$
\prod_{j\in\omega}K_j/\mathfrak{p},
$$

even though, in this,  $\partial_i \alpha = 0$  for all i in  $\omega$ , so  $\alpha$  has a p-th root in some extension. Thus the ultraproduct is not e.c.. Therefore the class of e.c. models of  $\omega$ -DF is not elementary.

## Theorem (P.).

$$
m\text{-DCF}_0 \subseteq (m+1)\text{-DCF}_0,
$$

and therefore  $\omega$ -DF<sub>0</sub> has a model-companion,  $\omega$ -DCF<sub>0</sub>, which is stable, but not superstable.

This is established by means of:

**Theorem** (folklore, P.). Assuming  $T_0 \subseteq T_1$ , each  $T_k$  having signature  $\mathscr{S}_k$ , consider:

A. If

$$
\mathfrak{A}\models T_1,\qquad \qquad \mathfrak{B}\models T_0,\qquad \qquad \mathfrak{A}\restriction \mathscr{S}_0\subseteq \mathfrak{B},
$$

then there is  $\mathfrak{C}$  such that

$$
\mathfrak{C} \models T_1, \qquad \mathfrak{A} \subseteq \mathfrak{C}, \qquad \mathfrak{B} \subseteq \mathfrak{C} \upharpoonright \mathscr{S}_0.
$$

B. For all  $\mathfrak{A}$ ,

$$
\mathfrak{A}\models_{\mathrm{ec}} T_1 \implies \mathfrak{A}\upharpoonright \mathscr{S}_0 \models_{\mathrm{ec}} T_0.
$$

- $C.$   $T_0$  has the Amalgamation Property: *if one model embeds in* two others, then those two in turn embed in a fourth model, compatibly with the original embeddings.
- D.  $T_1$  is  $\forall \exists$  (so that every model embeds in an e.c. model).

We have the two implications

$$
A \implies B, \qquad B \& C \& D \implies A,
$$

but there is no implication among the four conditions that does not follow from these. This is true, even if  $T_1$  is required to be a conservative extension of  $T_0$ , so that  $T_1 \restriction \mathscr{S}_0 = T_0$ .

Proof. (Can be left as exercise.) Suppose A holds. Let

$$
\mathfrak{A} \models_{\rm ec} T_1, \qquad \mathfrak{B} \models T_0, \qquad \mathfrak{A} \upharpoonright \mathscr{S}_0 \subseteq \mathfrak{B}.
$$

We show

$$
\mathfrak{A}\restriction \mathscr{S}_0 \preccurlyeq_1 \mathfrak{B}
$$

(*i.e.* every existential formula over  $\mathfrak{A} \restriction \mathscr{S}_0$  soluble in  $\mathfrak{B}$  is soluble in  $\mathfrak{A} \restriction \mathscr{S}_0$ . By hypothesis, there is a model  $\mathfrak{C}$  of  $T_1$  such that

$$
\mathfrak{A}\subseteq \mathfrak{C}, \qquad \qquad \mathfrak{B}\subseteq \mathfrak{C}\restriction \mathscr{S}_0.
$$

Then

$$
\mathfrak{A} \preccurlyeq_1 \mathfrak{C},
$$
  

$$
\mathfrak{A} \upharpoonright \mathscr{S}_0 \preccurlyeq_1 \mathfrak{C} \upharpoonright \mathscr{S}_0,
$$
  

$$
\mathfrak{A} \upharpoonright \mathscr{S}_0 \preccurlyeq_1 \mathfrak{B}.
$$

Therefore  $\mathfrak{A} \restriction \mathscr{S}_0$  must be an e.c. model of  $T_0$ . Thus B holds.

Suppose conversely  $B \& C \& D$  holds. Let

$$
\mathfrak{A}\models T_1,\qquad\qquad\mathfrak{B}\models T_0,\qquad\qquad\mathfrak{A}\restriction\mathscr{S}_0\subseteq\mathfrak{B}.
$$

We establish the consistency of

 $T_1 \cup \text{diag}(\mathfrak{A}) \cup \text{diag}(\mathfrak{B}).$ 

It is enough to show the consistency of

$$
T_1 \cup \text{diag}(\mathfrak{A}) \cup \{ \exists \vec{x} \ \varphi(\vec{x}) \},
$$

where  $\varphi$  is an arbitrary quantifier-free formula of  $\mathscr{S}_0(A)$  such that

$$
\mathfrak{B} \models \exists \vec{x} \ \varphi(\vec{x}).
$$

By  $D$ , there is  $\mathfrak C$  such that

$$
\mathfrak{C}\models_{\mathrm{ec}} T_1,\qquad \qquad \mathfrak{A}\subseteq \mathfrak{C}.
$$

By  $B$  then,

$$
\mathfrak{C} \upharpoonright \mathscr{S}_0 \models_{\mathrm{ec}} T_0, \qquad \qquad \mathfrak{A} \upharpoonright \mathscr{S}_0 \subseteq \mathfrak{C} \upharpoonright \mathscr{S}_0.
$$

By C, both  $\mathfrak{B}$  and  $\mathfrak{C} \restriction \mathscr{S}_0$  embed over  $\mathfrak{A} \restriction \mathscr{S}_0$  in a model  $\mathfrak{D}$  of  $T_0$ . In particular,

$$
\mathfrak{D} \models \exists \vec{x} \ \varphi(\vec{x}).
$$

Therefore  $\varphi$  is already soluble in  $\mathfrak{C} \restriction \mathscr{S}_0$  itself. Thus

$$
\mathfrak{C} \models T_1 \cup \text{diag}(\mathfrak{A}) \cup \{ \exists \vec{x} \ \varphi(\vec{x}) \}.
$$

Therefore A holds.

For the rest,  $11$  (counter-)examples are found...

Now suppose

$$
(L, \partial_0, \dots, \partial_{m-1}) \models m\text{-DF}_0,
$$
  
\n
$$
K \subseteq L,
$$
  
\n
$$
(K, \partial_0 \restriction K, \dots, \partial_{m-1} \restriction K, \partial_m) \models (m+1)\text{-DF}_0,
$$
  
\n
$$
a \in L \setminus K.
$$

We shall define a differential field

$$
(K\langle a\rangle, \tilde{\partial}_0,\ldots,\tilde{\partial}_m),
$$

where  $a \in K\langle a \rangle$ , and for each i in m,

$$
\tilde{\partial}_i \restriction K\langle a \rangle \cap L = \partial_i \restriction K\langle a \rangle \cap L,\tag{\dagger}
$$

and  $\tilde{\partial}_m \restriction K = \partial_m$ .

Considering  $\omega^{m+1}$  as the set of  $(m+1)$ -tuples of natural numbers, we shall have

$$
K\langle a\rangle = K(a^{\sigma} : \sigma \in \omega^{m+1}),
$$

where

$$
a^{\sigma} = \tilde{\partial}_0{}^{\sigma(0)} \cdots \tilde{\partial}_m{}^{\sigma(m)} a. \tag{\ddagger}
$$

In particular then, by  $(\dagger)$ , we must have

$$
\sigma(m) = 0 \implies a^{\sigma} = \partial_0^{\sigma(0)} \cdots \partial_{m-1}^{\sigma(m-1)} a. \tag{§}
$$

 $\,7$ 

 $\Box$ 

Using this rule, we make the definition

$$
K_1 = K(a^{\sigma} : \sigma(m) = 0).
$$

Recursively, we can define

$$
K_j = K(a^\sigma \colon \sigma(m) < j)
$$

as desired. If  $L \setminus K\langle a \rangle \neq \emptyset$ , we can repeat, as necessary. It may not be possible to make  $L$  itself closed under  $\tilde{\partial}_m.$